

# **Standard Finite Elements and Weighted Regularization**

**A Rehabilitation**

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## Outline

- Eigen-problem for Maxwell equations. “Regularization” by the interior term

$$(u, v) \longmapsto \int_{\Omega} s \operatorname{div} u \operatorname{div} v \, dx.$$

- Reentrant corners: Non- $H^1$  singularities cannot be approximated by nodal elements.
- Boundary penalization: A lesson on theory vs practice

$$(u, v) \longmapsto \lambda \int_{\partial\Omega} (u \times n) \cdot (v \times n) \, d\sigma.$$

- Weighted regularization: Convergence restored
- Convergence rates

## Maxwell eigenvalue problem

Permittivity  $\varepsilon$  and permeability  $\mu$ . Find non-zero  $\omega$  such that  $\exists (E, H) \neq 0$

$$\text{(Maxwell)} \quad \begin{cases} \text{rot } E - i\omega \mu H = 0 & \& \quad \text{rot } H + i\omega \varepsilon E = 0 \quad \text{in } \Omega, \\ E \times n = 0 & \& \quad H \cdot n = 0 \quad \text{on } \partial\Omega \end{cases}$$

(perfect conductor boundary conditions).

Homogeneous and isotropic medium:  $\varepsilon, \mu$  constant  $> 0$ . May assume  $\varepsilon = \mu = 1$ .

$$\implies \quad \text{div } E = 0 \quad \& \quad \text{div } H = 0$$

An “electric” variational formulation: Find non-zero  $\omega$  such that

$$\exists E \in H_0(\text{rot}; \Omega) \setminus \{0\} \text{ solves } \forall \tilde{E} \in H_0(\text{rot}; \Omega)$$

$$(1) \quad \int_{\Omega} \text{rot } E \cdot \text{rot } \tilde{E} = \omega^2 \int_{\Omega} E \cdot \tilde{E}$$



**Non-elliptic bvp:  $\infty$ -dim. e-space for  $\omega = 0$  (does not satisfy  $\text{div } E = 0$ ).**

## A first strategy : edge elements

The infinite dimensional eigen-space  $\mathfrak{E}_0$  for  $\omega = 0$  is

$$\mathfrak{E}_0 = \{E = \text{grad } \varphi \mid \varphi \in H_0^1(\Omega)\}.$$

Unless divergence-free elements are used (?), the space  $\mathfrak{E}_0$  has an influence on any discrete scheme. The spurious modes are also approximated. If they are approximated by non-zero eigen-frequencies, they pollute the whole spectrum.

Generalized pollution is avoided by the use of *spurious free elements* (if they exist !), that is, discrete spaces where the 0 e-value is approached by exact 0.

Such elements do exist:

they are realized by the 2 generations of NEDELEC's edge elements (1980 and 1986).

These discrete families are rot conforming but not div conforming.

The compatibility conditions between two neighboring elements are obtained via *moments across the common edge*.

## An alternative strategy : Nodal FEMs need Regularization

The electric field  $E$  solution of the Maxwell e-value problem belongs to

$$X_N = \left\{ u \in L^2(\Omega)^3 ; \operatorname{rot} u \in L^2(\Omega)^3, \operatorname{div} u \in L^2(\Omega), u \times n = 0 \text{ on } \partial\Omega \right\}.$$

Reintroduce the divergence via a regularization parameter  $s > 0$ , i.e. add

$$s \langle \operatorname{div} E, \operatorname{div} \tilde{E} \rangle.$$

$\implies$  Variational formulation in  $X_N$ . For  $s > 0$ , find non-zero  $\omega[s]$

$\exists E \in X_N \setminus \{0\}$  solves  $\forall \tilde{E} \in X_N$

$$\int_{\Omega} \operatorname{rot} E \cdot \operatorname{rot} \tilde{E} + s \operatorname{div} E \operatorname{div} \tilde{E} = \omega[s]^2 \int_{\Omega} E \cdot \tilde{E}.$$

The solutions  $\omega$  independent of  $s$  are the Maxwell e-frequencies.

Spurious eigenfrequencies:  $\omega[s]^2 = s\nu$  with Dirichlet eigenvalues  $\nu$ .

Elliptic bvp:  $s = 1$ : Laplacian;  $s > 1$ : Lamé with  $\mu = 1, \lambda = s - 2$ .

Coercive bilinear form; stability and convergence of FEM...

However .../...

## A topological barrier

Any  $X_N$ -conforming finite element space  $\mathfrak{X}_N^h$  is contained in  $\mathcal{C}^0(\overline{\Omega})$

$\implies \mathfrak{X}_N^h$  is  $H^1$ -conforming

$\implies$  The solution of the Galerkin approximation in  $\mathfrak{X}_N^h$ ,  $E_h \in H^1(\Omega)^3$  thus to

$$H_N := X_N \cap H^1(\Omega)^3.$$

Let  $H_N^\infty := \mathcal{C}^\infty(\overline{\Omega})^3 \cap X_N$ . For  $u \in H_N^\infty$  there holds

$$\int_{\Omega} |\operatorname{rot} u|^2 + |\operatorname{div} u|^2 = \int_{\Omega} |\operatorname{grad} u|^2.$$

Thus the closure  $\overline{H}_N^\infty$  of  $H_N^\infty$  for the norm  $(\|u\|^2 + \|\operatorname{rot} u\|^2 + \|\operatorname{div} u\|^2)^{1/2}$  is contained in  $H_N$ . In fact

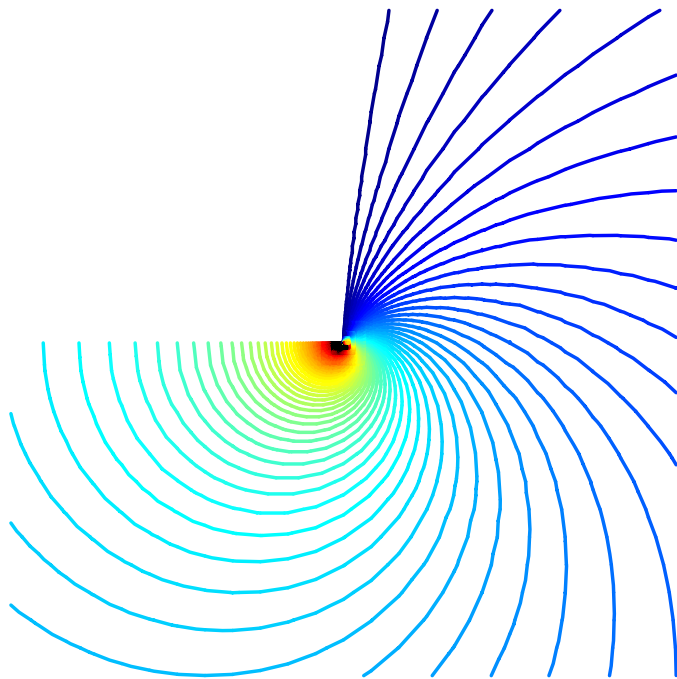
$$\overline{H}_N^\infty = H_N$$

$\implies E_h$  converges to  $E_{\text{wr}} \in H_N$ .

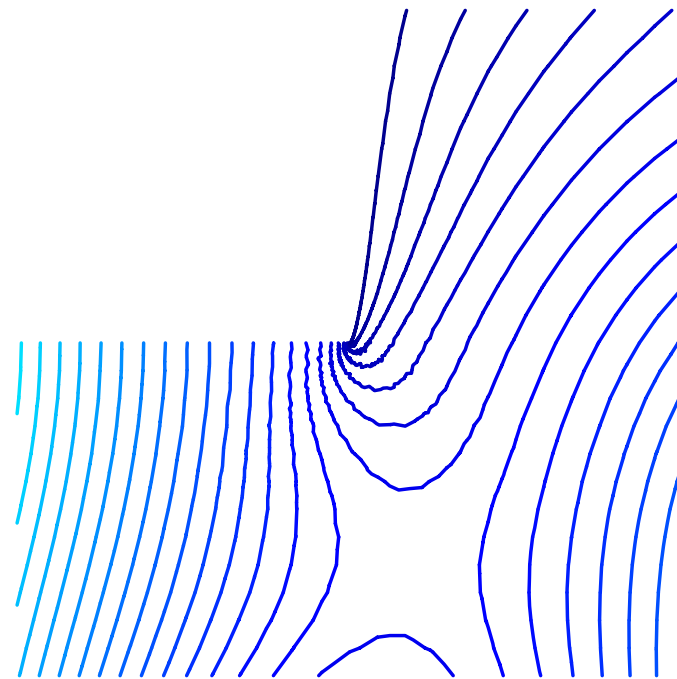
And  $E_{\text{wr}}$  is wrong, because for non-convex polyhedra  $H_N \neq X_N$ .

## The standard nodal “approximation” of the first singularity

The exact solution  $(\text{grad}(r^{\frac{2}{3}} \sin \frac{2\theta}{3}))_1$ .



Computation with  $\mathbb{Q}_3$  elements.



**Non- $H^1$  singularities are not approximated.**

## Variational singularities derive from potentials

Any  $\text{grad } \varphi$  with  $\varphi \in D(\Delta^{\text{Dir}})$  belongs to  $X_N$ , where

$$D(\Delta^{\text{Dir}}) = \{\varphi \in H_0^1(\Omega) ; \Delta\varphi \in L^2(\Omega)\}.$$

For non-convex polyhedra,  $\exists K_{\text{Dir}} \neq \{0\}$  such that

$$(H^2 \cap H_0^1(\Omega)) \oplus K_{\text{Dir}} = D(\Delta^{\text{Dir}}).$$

There holds

$$X_N = H_N \oplus \text{grad}(K_{\text{Dir}})$$

3D : For non-convex polyhedra,  $\dim K_{\text{Dir}} = +\infty$

2D : For non-convex polygons,  $\dim K_{\text{Dir}} = \# \text{nonconvex corners}$



## Boundary penalization

Boundary-penalized bilinear form  $a[s, \lambda]$  defined on  $W$  as

$$\int_{\Omega} \operatorname{rot} E \cdot \operatorname{rot} \tilde{E} + s \operatorname{div} E \operatorname{div} \tilde{E} + \lambda \int_{\partial\Omega} (E \times n) \cdot (\tilde{E} \times n),$$

with the variational space

$$W = \{E \in H(\operatorname{rot}) \cap H(\operatorname{div}); E \times n|_{\partial\Omega} \in L^2(\partial\Omega)\}.$$

**Theorem [CoDa'98]:**  $\Omega$  Lipschitz domain:  $C^\infty(\overline{\Omega})^3$  is dense in  $W$ .

Spurious eigenfrequencies (the same):  $\omega[s, \lambda]^2 = s\nu$  with Dirichlet eigenvalues  $\nu$ .

The solutions  $\omega[s, \lambda]$  independent of  $s$  tend to the Maxwell e-frequencies

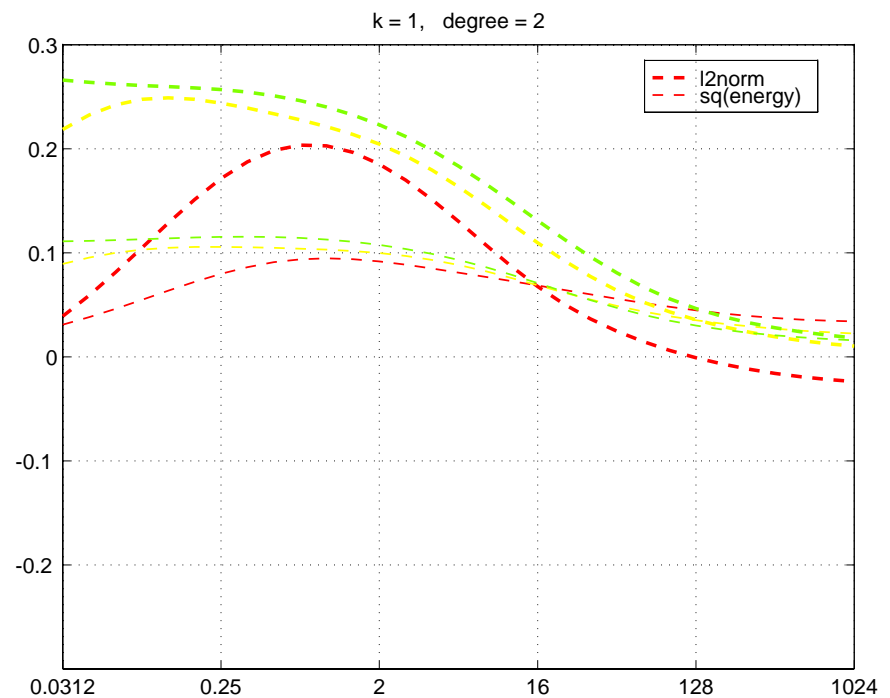
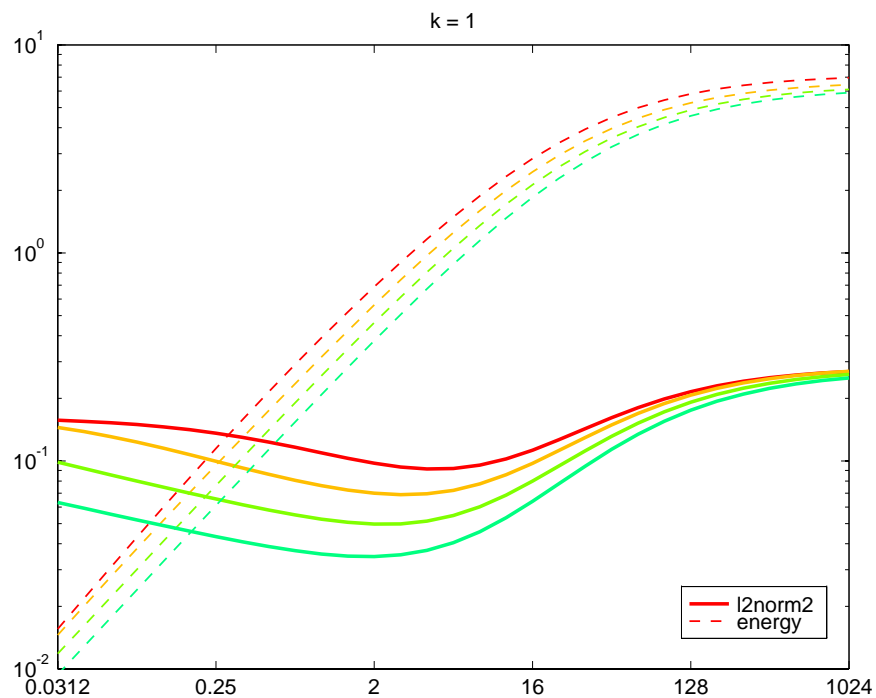
$$|\omega[s, \lambda] - \omega[s]| = \mathcal{O}\left(\frac{1}{\lambda}\right) \quad \text{as } \lambda \rightarrow \infty$$

However, convergence rates... are not known, and practical convergence is very poor.

## Boundary penalization : non promising results

Comput. of 1<sup>st</sup> singularity with  $\mathbb{P}_2$  elements in 4 nested regular triangular meshes.

Quadratic errors and convergence rates for  $s = 1$  and  $\lambda$  from  $2^{-5}$  to  $2^{10}$ .



## Weighted regularization : The idea

Regularize the divergence via a term  $s \langle \operatorname{div} E, \operatorname{div} \tilde{E} \rangle_Y$  with an intermediate space

$$L^2(\Omega) \subset Y \subset H^{-1}(\Omega).$$

The variational space is then

$$X_N[Y] = \{E \in H_0(\operatorname{rot}) \mid \operatorname{div} E \in Y\}.$$

We take  $Y$  as a weighted  $L^2$  space:

$$\langle \operatorname{div} E, \operatorname{div} \tilde{E} \rangle_Y = \int_{\Omega} \sigma \operatorname{div} E \operatorname{div} \tilde{E} \, dx$$

where

$$\sigma(x) = d(x)^\alpha \quad \text{with} \quad 0 \leq \alpha \leq 2$$

with  $d(x) = \operatorname{dist}(x, \mathfrak{S})$  the distance function to the set  $\mathfrak{S}$  of

**non-convex corners** for a polygon and **non-convex edges** for a polyhedron.

## Weighted penalization : A density result

Define the Laplace-Dirichlet operator  $\Delta^{\text{Dir}}[Y]$  as

$$\Delta^{\text{Dir}}[Y] : \mathcal{D}(\Delta^{\text{Dir}}[Y]) := \{\varphi \in H_0^1(\Omega) \mid \Delta\varphi \in Y\} \begin{array}{l} \longrightarrow Y \\ \varphi \longmapsto \Delta\varphi. \end{array}$$

**Theorem [CoDa'00] :**

(i) Any element  $u \in X_N[Y]$  can be decomposed into the sum

$$u = w + \text{grad } \varphi, \quad \text{with } w \in H_N \text{ and } \varphi \in \mathcal{D}(\Delta^{\text{Dir}}[Y]).$$

(ii) If  $H^2 \cap H_0^1(\Omega)$  is dense in  $\mathcal{D}(\Delta^{\text{Dir}}[Y])$  for the graph norm, then  $H_N$  is dense in  $X_N[Y]$ .

(iii)  $H^2 \cap H_0^1(\Omega)$  is closed in  $\mathcal{D}(\Delta^{\text{Dir}}[Y])$  if and only if  $H_N$  is closed in  $X_N[Y]$ .

(iv)  $\mathcal{D}(\Delta^{\text{Dir}}[Y])$  is contained in  $H^2(\Omega)$  if and only if  $X_N[Y] = H_N$ .

## How to choose the weight for a polyhedron

Edges  $e$ , opening angles  $\omega_e$ .

Corners  $c$ , Laplace Dirichlet singularity exponents  $\lambda_c^{\text{Dir}}$ .

With  $d(x) = \text{dist}(x, \mathfrak{S})$  the distance to the set  $\mathfrak{S}$  of **non-convex edges**, the weight  $\sigma$  is defined as (we set  $\alpha = 2\gamma$ )

$$\sigma(x) = d(x)^{2\gamma} \quad \text{with} \quad 0 \leq \gamma \leq 1$$

When  $\gamma$  is close enough to 1, the domain  $\mathcal{D}(\Delta^{\text{Dir}}[Y])$  is a weighted space  $V_\gamma^2(\Omega)$  of KONDRAT'EV type and the smooth functions are dense :

**Theorem [CoDa'00] :**

*If* 
$$\max_{e,c} \left\{ 1 - \frac{\pi}{\omega_e}, \frac{1}{2} - \lambda_c^{\text{Dir}} \right\} < \gamma \leq 1$$

*then* 
$$H_N \text{ is dense in } X_N[Y]$$

$\Rightarrow$

Any Galerkin method converges.

## Approximation properties of the FEM spaces

The Maxwell eigenvectors  $E$  admit the following splitting

$$E = w + \text{grad } \varphi, \quad \text{with } w \in H_N \text{ and } \varphi \in \mathcal{D}(\Delta^{\text{Dir}}[Y]).$$

In fact,  $w$  belongs to a space  $H_N^{\text{Neu}} \subset H_N$  where each component has the same regularity as solutions of the Neumann problem for  $\Delta$  with a  $L^2$  rhs and  $\varphi$  belongs to a weighted space  $K_{\text{Dir}}^\infty$  determined by the only Dirichlet singularity exponents.

**Assumptions on the FEM spaces  $\mathfrak{X}_N^h$  :**  $\exists \tau > 0$

$$(\mathfrak{A}_1) \quad \forall w \in H_N^{\text{Neu}}, \quad \inf_{w_h \in \mathfrak{X}_N^h} \|w - w_h\|_{H^1} \leq C h^\tau$$

$$(\mathfrak{A}_2) \quad \exists \Phi_h : \text{grad } \Phi_h \subset \mathfrak{X}_N^h, \text{ so that } \forall \varphi \in K_{\text{Dir}}^\infty, \quad \inf_{\varphi_h \in \Phi_h} \|\varphi - \varphi_h\|_{V_\gamma^2} \leq C h^\tau$$

**Theorem [CoDa'01] :** *Estimate between e-vector  $E$  and e-vector  $E_h \in \mathfrak{X}_N^h$  :*

$$\|E - E_h\|_{X_N[Y]} \leq C(E) h^\tau$$

## Convergence rates in 2D

The FEM spaces  $\mathcal{X}_N^h$  of nodal elements originating from

- $\mathbb{Q}_q$  rectangles for  $q \geq 3$ ,
- $\mathbb{P}_q$  triangles for  $q \geq 4$  ( $q \geq 2$  on some triangulations),

on a  $h$ -uniform mesh, satisfy Assumptions  $(\mathfrak{A}_1) - (\mathfrak{A}_2)$  as soon as  $\gamma$  satisfies

$$\max_e \left\{ 1 - \frac{\pi}{\omega_e} \right\} < \gamma \leq 1$$

for any  $\tau$  such that

$$\tau < \min \left\{ \frac{\pi}{\omega_0} - 1 + \gamma, \frac{\pi}{\omega_1} - 1 \right\}$$

where  $\omega_0$  is the largest non-convex angle and  $\omega_1$  the largest convex angle.

For the L-shaped domain, we obtain

$$\tau < \gamma - \frac{1}{3}, \quad \text{and for the optimal value } \gamma = 1, \tau < \frac{2}{3}.$$

## Illustration: Maxwell eigenvalues in a polygon

**E-modes**  $(\Lambda[s], u[s])$  of the parameter-dependent problems associated with  $a[s]$

$$s \geq 0 : a[s](u, v) = \int_{\Omega} (\text{rot } u \text{ rot } v + s r^{\alpha} \text{ div } u \text{ div } v) dx.$$

Here  $\text{rot } u = \partial_1 u_2 - \partial_2 u_1$  and  $\text{div } u = \partial_1 u_1 + \partial_2 u_2$ .

The e-modes  $(\Lambda[s], u[s])$  in  $X_N$  can be organized in 2 types

1)  $\Lambda[s]$  independent of  $s$ : they are the Maxwell e-values.

$(\Lambda[s], u[s]) = (\nu, \overrightarrow{\text{rot}}\varphi)$  with the Neumann e-modes  $(\nu, \varphi)$  of  $-\Delta$ .

2)  $\Lambda[s]$  linear dependent on  $s$ : they are the spurious e-values.

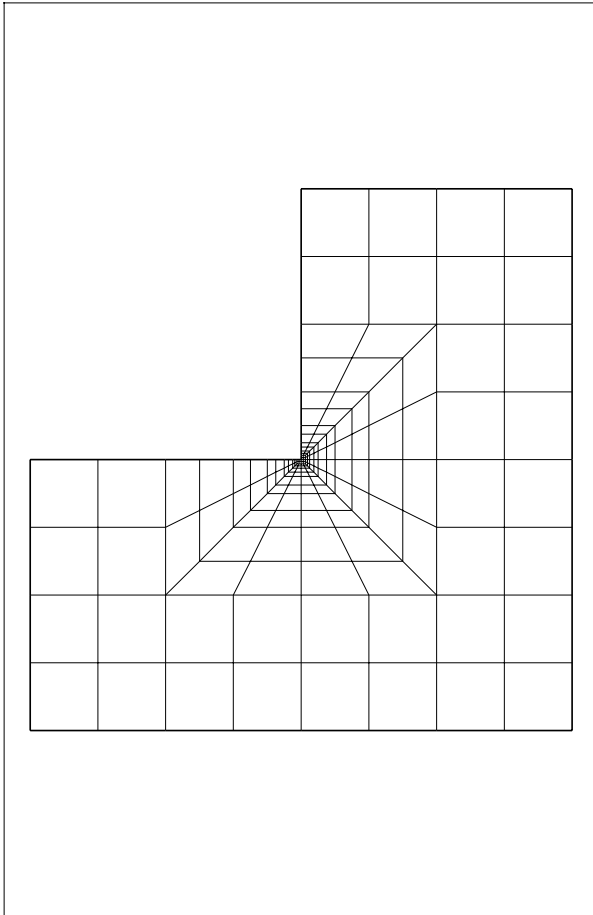
$(\Lambda[s], u[s]) = (s\nu, \overrightarrow{\text{grad}}\varphi)$  with the Dirichlet e-modes  $(\nu, \varphi)$  of the operator

$$-r^{\alpha/2} \Delta r^{\alpha/2}.$$



## Computations

$\Omega$  is the  $L$ -shape domain :  $[0.5, 1] \times [0.5, 1] \setminus [0.75, 1] \times [0.75, 1]$ .



Computation of the first 15 eigenvalues and eigenvectors  $\Lambda[s]$  for

$$s = [2 : 100],$$

$$\alpha = 0, 1, 2,$$

$$q = 1, 2, 3, 4$$

with the FEM library MÉLINA by D. MARTIN.

The computed eigenvalues are sorted depending on whether

$$\frac{\|\text{rot } u\|^2}{s\|r^{\alpha/2} \text{div } u\|^2}$$

is  $\geq \rho$  or  $\leq \rho^{-1}$  with a fixed  $\rho \geq 1$ .

## Legend

For the next 8 figures.

In *Cyan*, the Laplace-Neumann eigenvalues, which coincide for 2D domains with Maxwell eigenvalues.

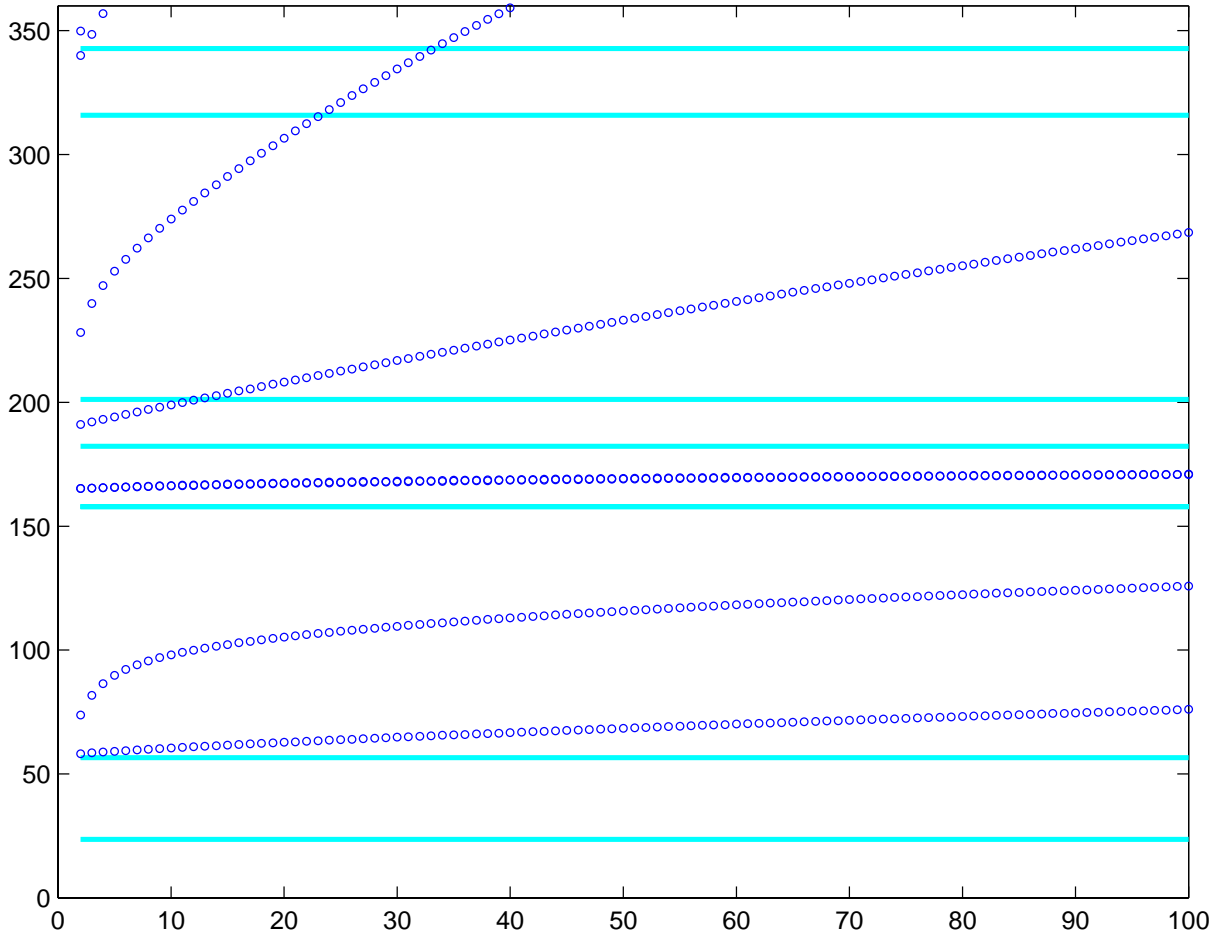
In *Blue*, the circles represent the computed  $\Lambda[s]$  with rot dominant eigenvectors.

In *Red*, the lines join the computed  $\Lambda[s]$  with div dominant eigenvectors.

**Abscissa :**  $s$

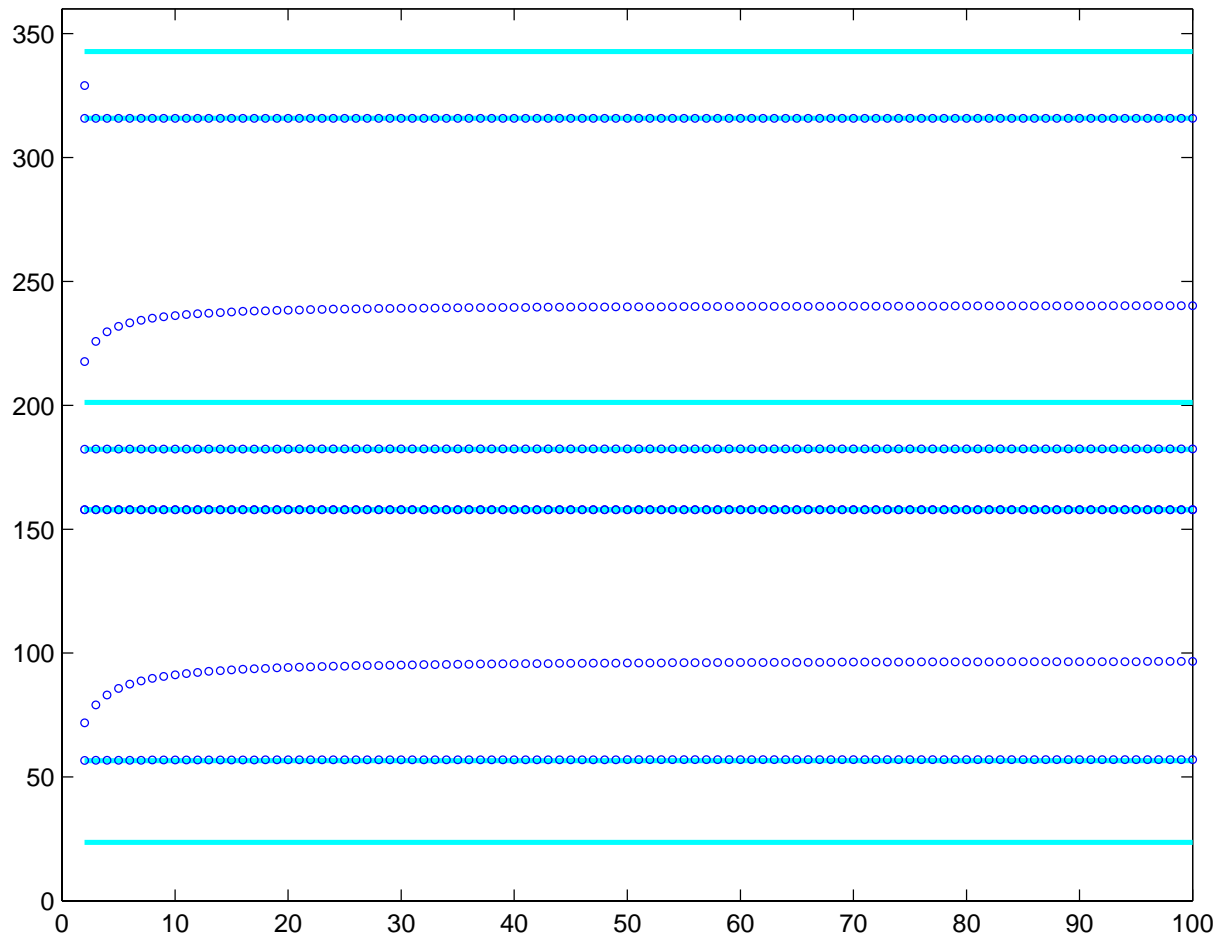
**Ordinate :**  $\Lambda[s]$ .

$q = 1, \alpha = 0$



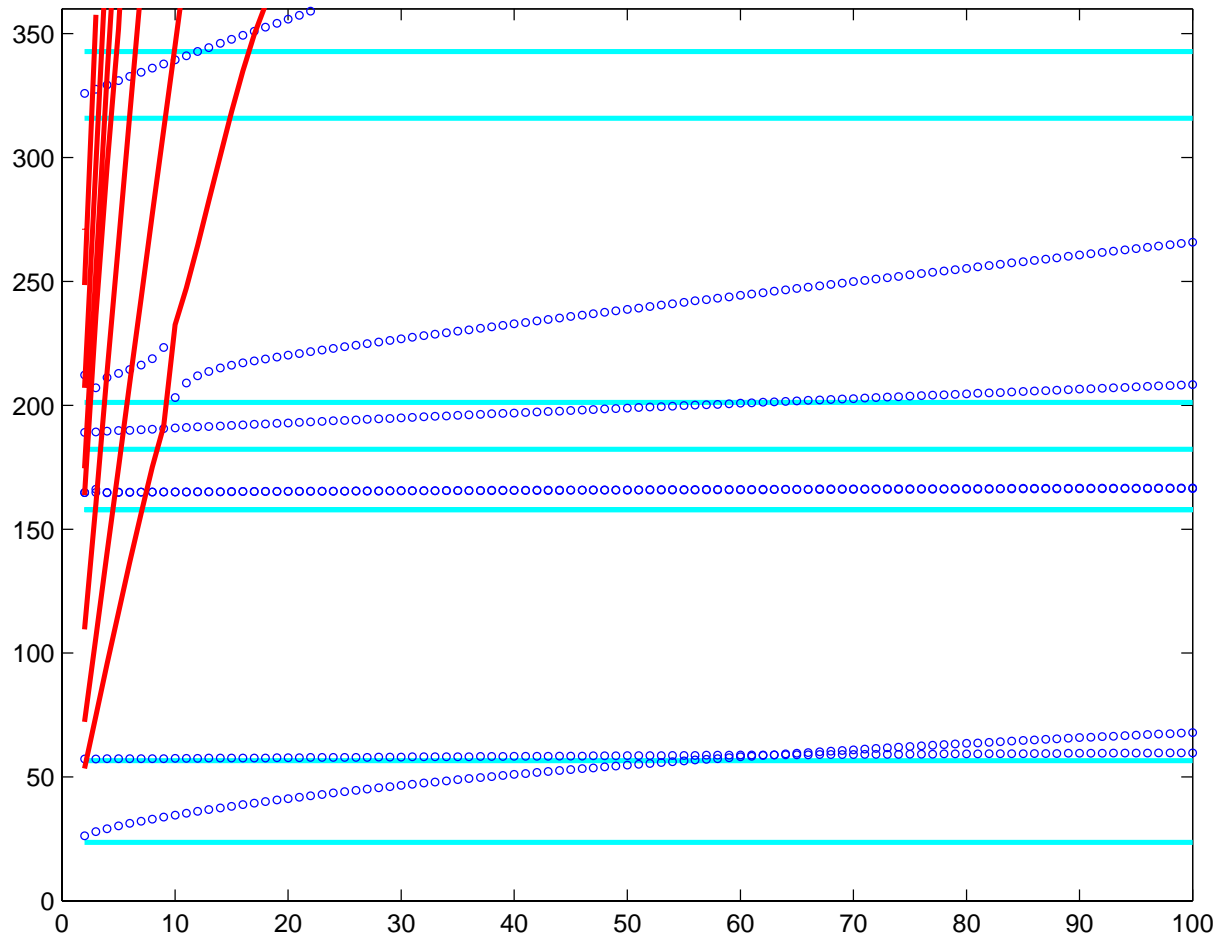
*Weighted Regularization of Maxwell Equations*

$$q = 4, \alpha = 0$$



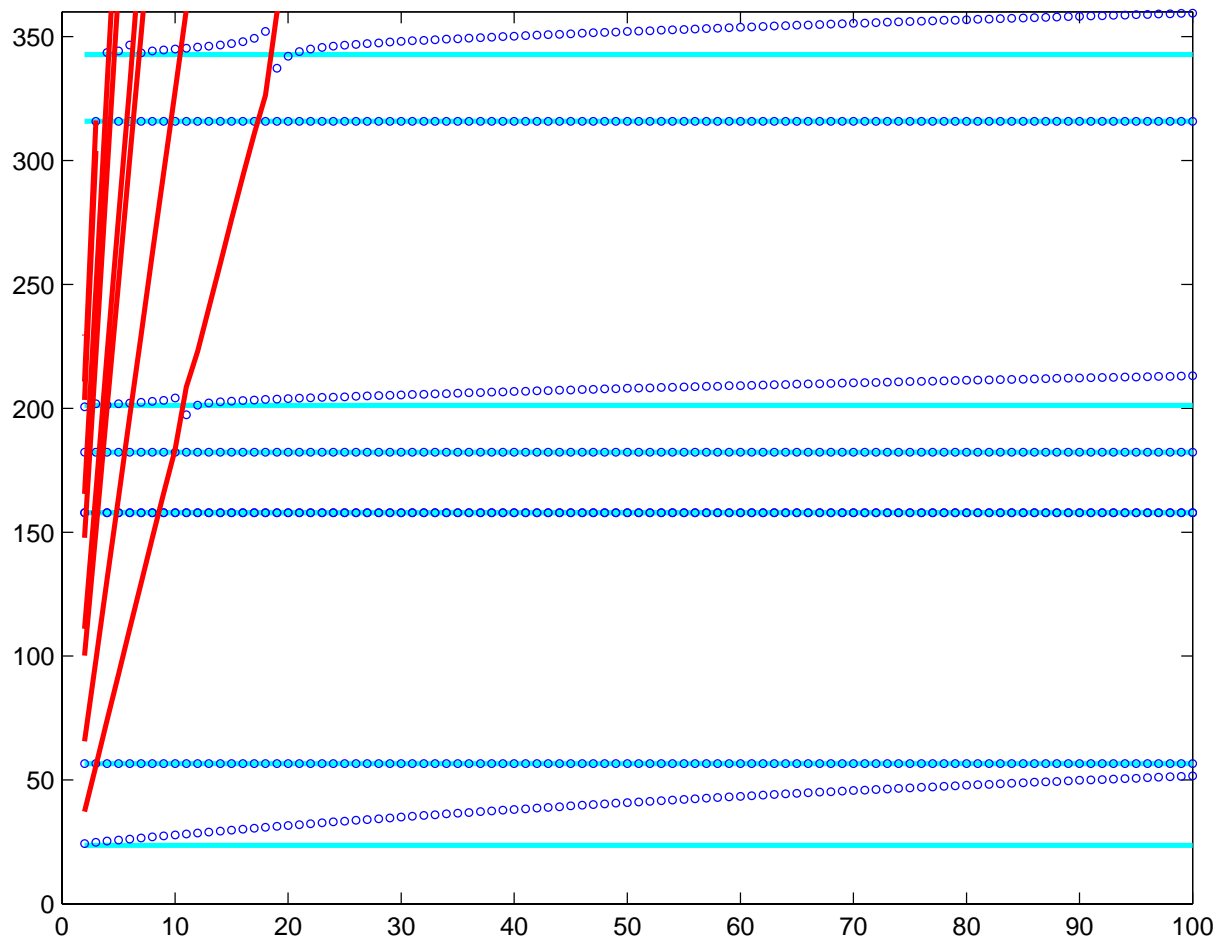
*Weighted Regularization of Maxwell Equations*

$$q = 1, \alpha = 1$$



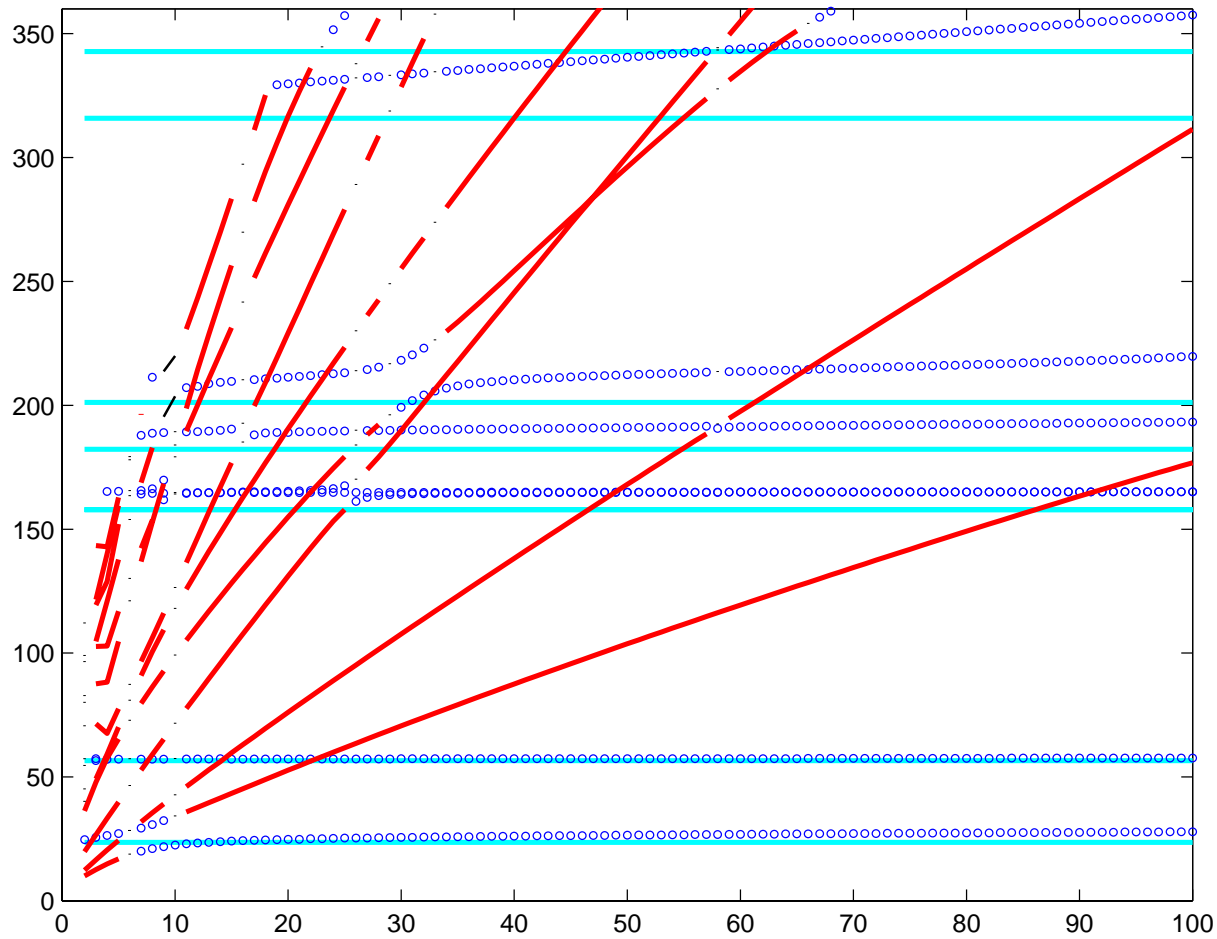
*Weighted Regularization of Maxwell Equations*

$$q = 4, \alpha = 1$$



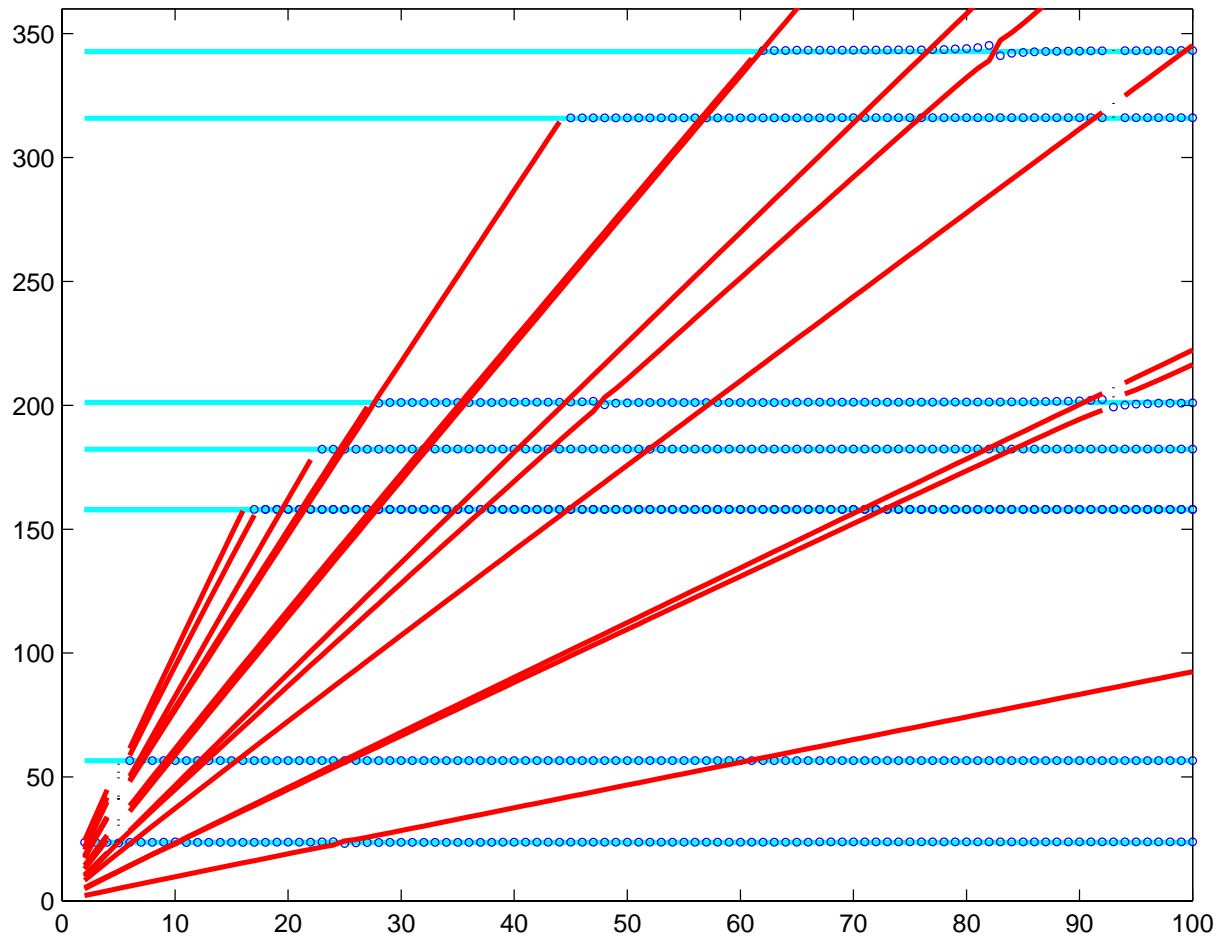
*Weighted Regularization of Maxwell Equations*

$$q = 1, \alpha = 2$$



*Weighted Regularization of Maxwell Equations*

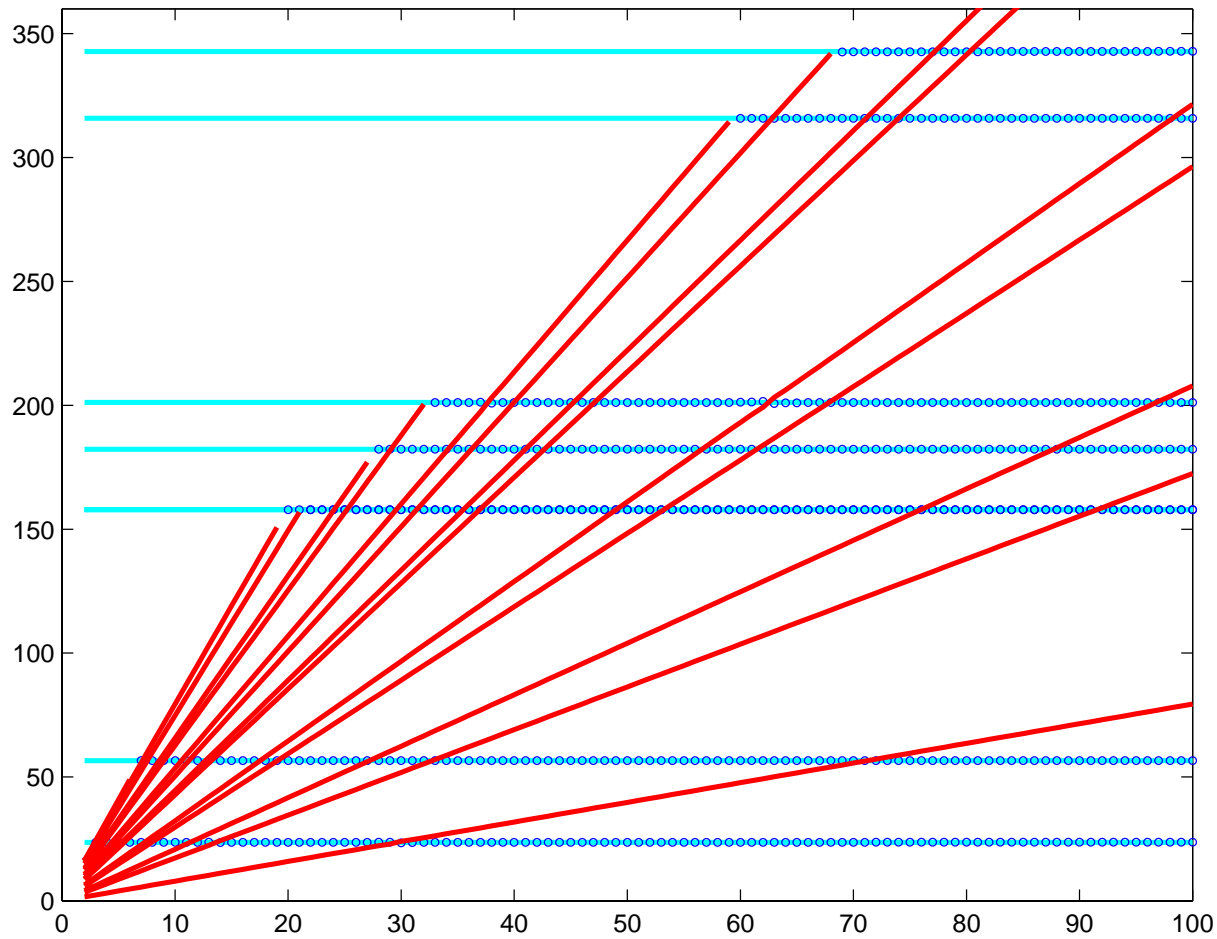
$$q = 2, \alpha = 2$$



*Weighted Regularization of Maxwell Equations*

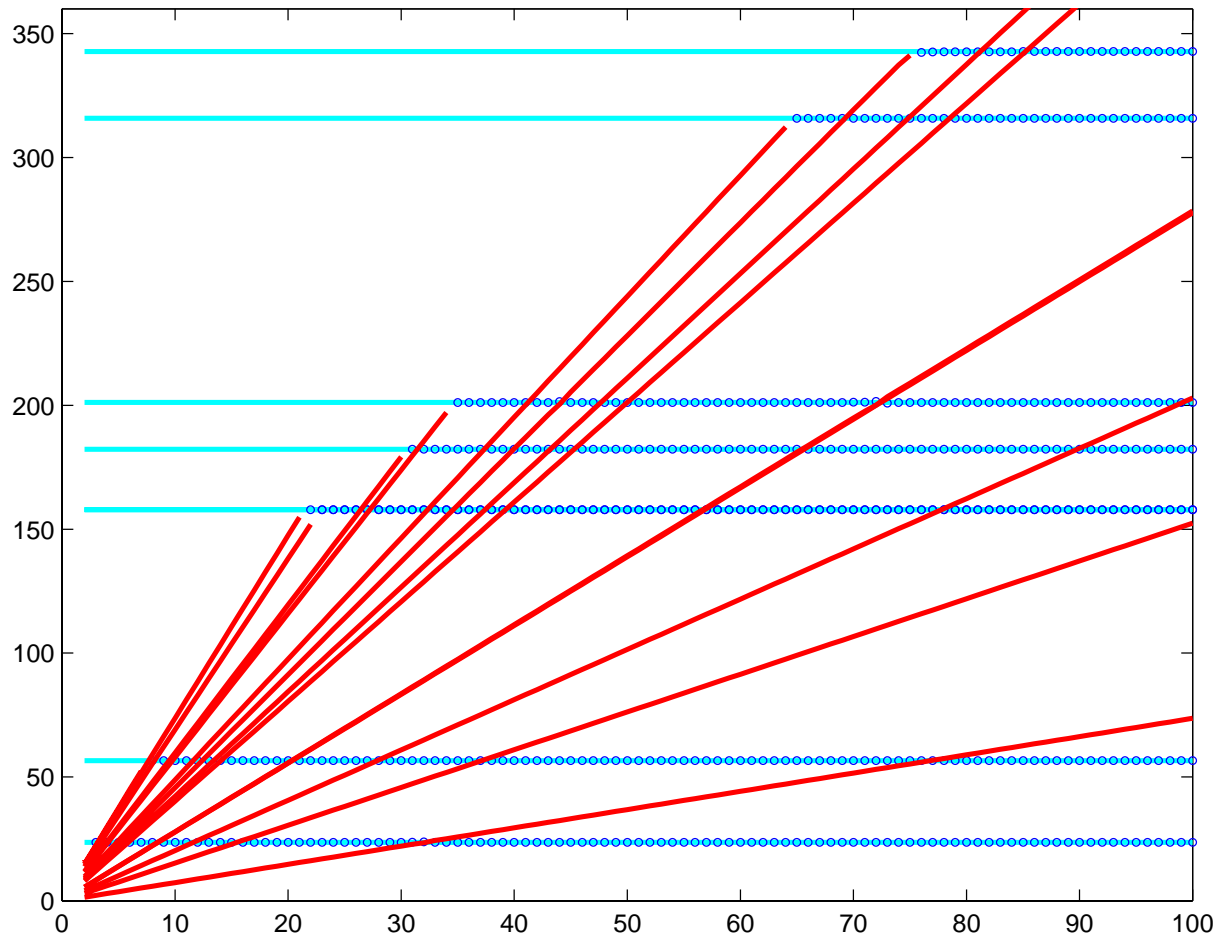


$$q = 3, \alpha = 2$$



*Weighted Regularization of Maxwell Equations*

$$q = 4, \alpha = 2$$



*Weighted Regularization of Maxwell Equations*